

Schedule

Monday

End-of-course Evaluations

Robot Parade: getting started

Office hours: 2:30-4:00

Tuesday

Office hours: 2:30-4:00

Wednesday

Status Reports

Robot Parade: working toward completion

Office hours: 2:30-4:00

Thursday

Office hours (no sign-ups): 2:30-4:00 (in lab)
and 5:00-7:00 (in lab)

Friday

Robot Parade in class

Office hours: 2:30-4:00

All coursework (extra credit labs & sup. problems, projects)

due by 5:00 pm CST official MathLAN time (both paper, email)

Submission $\geq$ 5:01 pm not accepted/graded

Don't even think about being late

Robot Parade Project

Overview

- robots line up
- when robots in front clear out
 - one lab partner at the keyboard types character(s)
 - robot moves forward slowly
- when robot reaches starting line
 - one lab partner at the keyboard types character(s)
 - robot follows commands read from a file

Overall, robots will

- start in classroom
- turn, beep, move forward in stages
- progress into hallway
- turn right
- move down hallway in front of classroom window

Robot Parade Project

3 main parts

- program to respond to input commands
 - based on robot command project
- adjust input for either user or file
 - based on command-line argument
- allow logging
 - option to record each robot action
 - motivation:
 - if user types sequence of commands
 - record each command (with parameters) in file
 - option details based on command-line argument

Robot Parade Project

likely development process

- start with robot command project
- add variables for file input/logging
 - defaults: stdin/NULL
 - use command-line arguments to set file variables
 - see Friday's class notes for command-line processing
- change input prompts/scanf to
 - if inputFile == stdin, then prompt
 - scanf becomes fscanf
 - clear line after processing each line
- add logging statement when loggingFile != NULL
 - print line with command and any needed parameters
- just one read/write section, with fscanf and possible logging for each command (not multiple read/write sections)